MBDC050-012031-120V
120VAC Input Brush DC Controller

User's Guide

MBDC050-012031-120V Driver Features

- *Fixed Current Limit Set at 3.0 Amps with an output power up to 18W*
- *0.5V to 5V External Voltage Speed Control*
- *2-Quadrant Operation*
- *Open-Loop Velocity Mode*
- *12VDC Motor Bus*
- *Requires 85-135 VAC Input*
- *Freewheel and Direction Inputs*
- *Cycle by Cycle Short Circuit Protection*
- *Compact Size (4.73" X 3.19" X 1.54")*
- *Screw Type Terminal Block*

General Description

The MBDC050-012031-120V driver is designed to drive DC brush motors at peak currents of up to 3.0A and 18W. The MBDC050-012031-120V is a compact, low profile package meant to be used where space is limited but performance is expected and eliminates the need for an external power supply. The driver has a motor bus voltage of 24V. An external potentiometer (10K) or external voltage (0.5-5VDC) can be used to control the speed. The direction of the motor can be preset by the direction control input. To disable energy from the motor, there is a Freewheel input that can enabled by allowing current through the input opto-diode.

Pin Descriptions

The inputs on the MBDC050-012031-120V are optically isolated. For the Direction and Freewheel opto-diodes the an anode (+) and cathode (-) where both are brought to the user. An analog voltage to control the speed is also optically isolated. With no current going through the Direction, Freewheel opto-diodes, the input is considered high. To enable the motor to Run, current must not go through the Freewheel input opto-diode and an analog voltage from 0.5V to 5V must be applied to VSPD. To Freewheel (remove energy from the motor) the motor, current must go through the Freewheel input opto-diode. To preset the direction of the motor, current must not go through the Direction input opto-diode (clockwise) or current must go through the Direction input opto-diode (counter clockwise). The Direction and Freewheel inputs are compatible from 3.5V to 24V.

Optically Isolated Inputs and Output

The following inputs and output to the MDC200-024051 are Optically Isolated:

Item	Pin #
ISO 5VOUT	1
ISO GND	3
Direction	4 & 5
Freewheel	6 & 7
VSPD*	2

*VSPD: 0.5 - 5V analog signal referenced to ISO GND.

Absolute Maximum Ratings

Vspeed Control: (TB1, Pin 2):	0VDC - Motor Stopped 5VDC - Max Speed (6VDC max)
Control Inputs (TB1, Pins 4-7):	3.5VDC - 24VDC 1mA minimum
Direction Control: (TB1, Pins 4 & 5)	Logic "1" (open) - Clockwise Logic "0" - Counterclockwise
Freewheel: (TB1, Pins 6 & 7)	Logic "1" (open) - Motor is Enabled Logic "0" - Motor is de-energized and will coast
ISO5VOUT Output: (TB1, Pin 1)	5.1V @ 50mA Maximum
Power Requirements: (TB3, Pins 1 & 2)	85VAC (min) - 132VAC (max)
Motor Voltage Bus:	12VDC
Motor Output Current:	3.0A peak (1.5A average) maximum operating current.
Operating Temperature:	0°C to 70°C

Heating Considerations

The temperature of the heat sink should never be allowed to rise above 70° Celsius. If necessary, mount the unit to an additional heat sink or air should be blown across the heat sink to maintain suitable temperatures.

Terminal Pin Out

Pin #	Description
1	ISO 5VOUT
2	VSPD
3	ISO GND
4	Direction +
5	Direction -
6	Freewheel +
7	Freewheel -

Pin #	Description
1	OUT 1
2	OUT 2

TB2: Motor Phase
 Terminals

Pin #	Description
1	AC Hot
2	AC Neutral
3	EARTH GND (must be connected)

TB3: AC Voltage In Terminals

TB1: Opto-isolated Control
Inputs, Outputs and Speed
Control

Terminal Descriptions

Motor Freewheel

The motor freewheel feature allows the de-energizing of the motor phases. A low at this input causes the motor to coast to a stop, while a high (open) input causes the motor to run at the given speed.

Motor Direction

The motor direction feature allows the changing of the rotation of the motor. This input should not be changed while motion is in progress. A low at this input causes the motor to turn in the CW direction, while a high (open) input causes the motor to turn in the CCW direction.
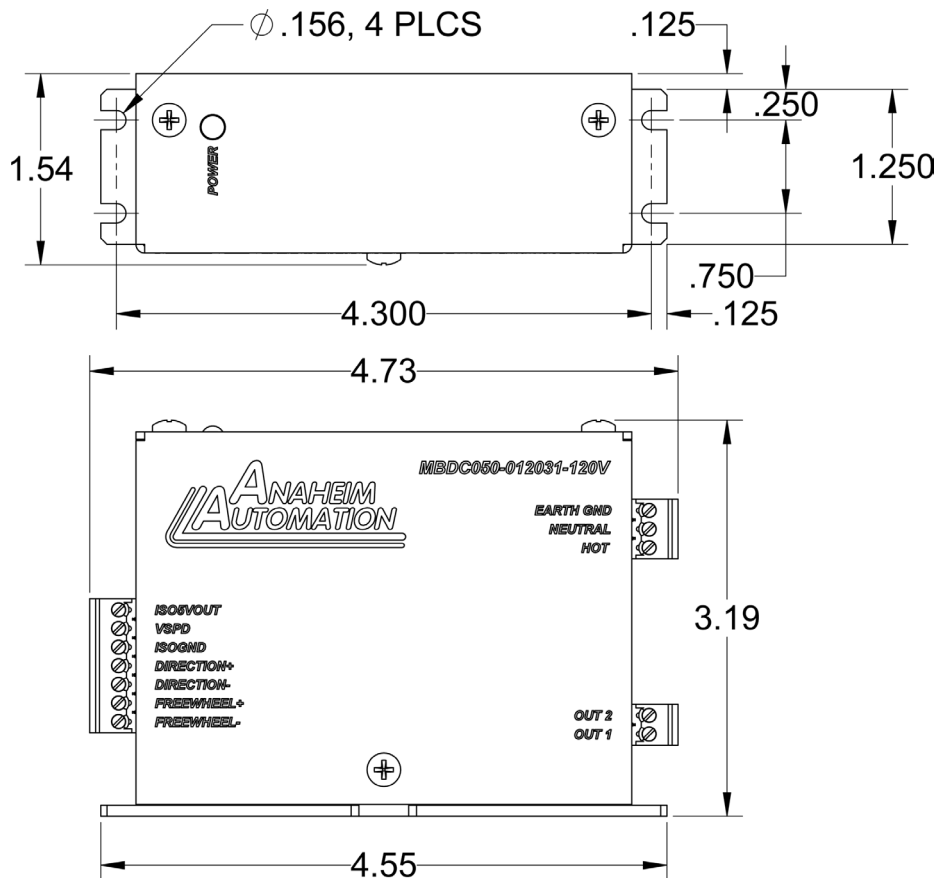
Speed Adjust, ISO 5V, and ISO GND

To adjust the motor speed, the external voltage input can be varied from 0.5V to 5V. An external potentiometer can be connected from ISO 5VOUT supply to ISO GND, with the wiper attached to VSPD.
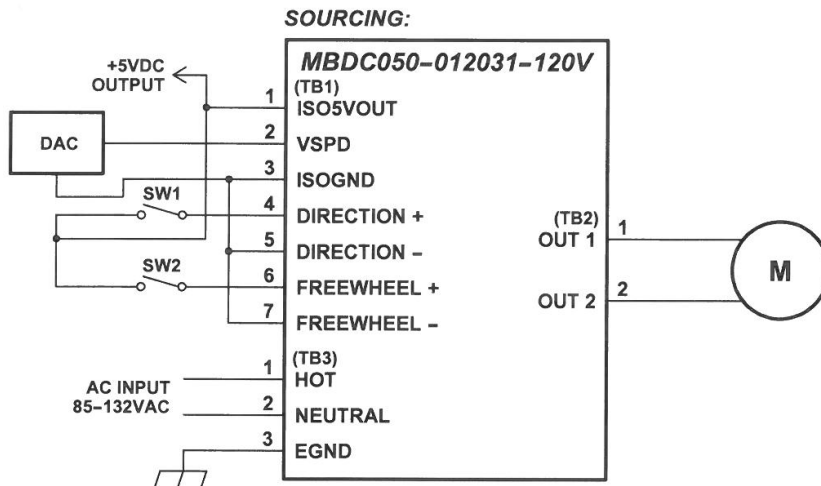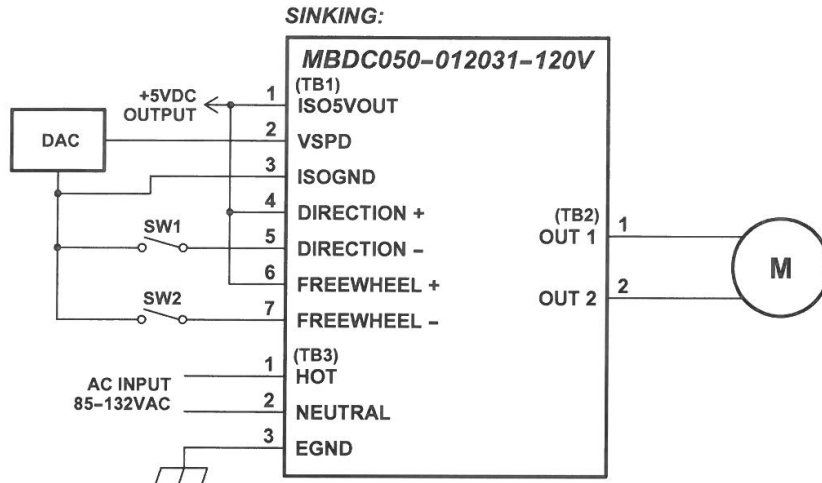
Fault Protection

If a fault occurs, the internal fault protection is activated and shutting off the motor output. If the fault remains after 1.2mS, the motor output shutoff will repeat. The fault conditons are:

1. Over Current. The driver is equipped with cycle-by-cycle current limiting at 3A.
2. Over Temperature on driver IC exceeding 120°C.
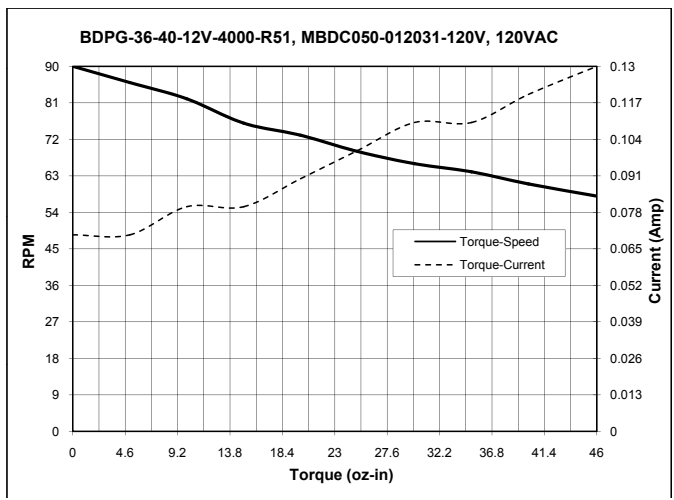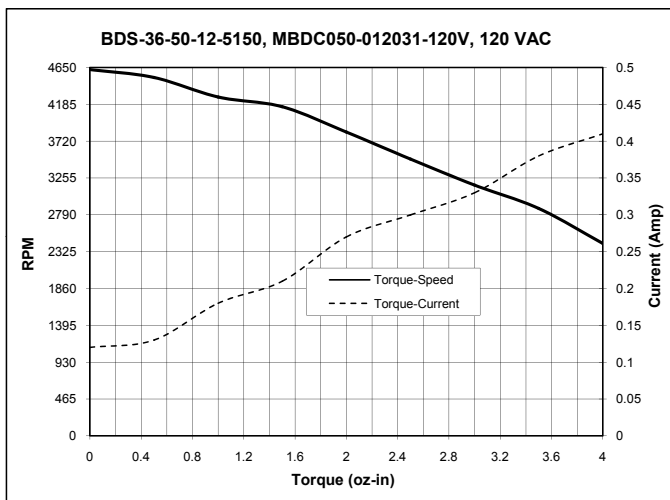3. Under-voltage Lockout activation at 6.5VDC for the motor bus caused by shorted AC input.

Dimensions

Typical Wiring Diagram

SINKING:

MBDC050-012031-120V

(TB1)
1 ISO5VOUT — +5VDC OUTPUT
2 VSPD — DAC
3 ISOGND
4 DIRECTION +
5 DIRECTION −   SW1
6 FREEWHEEL +   SW2
7 FREEWHEEL −

(TB2)
OUT 1   1 — M
OUT 2   2

(TB3)
1 HOT — AC INPUT 85–132VAC
2 NEUTRAL
3 EGND

SOURCING:

MBDC050-012031-120V

(TB1)
1 ISO5VOUT — +5VDC OUTPUT
2 VSPD — DAC
3 ISOGND
4 DIRECTION +   SW1
5 DIRECTION −
6 FREEWHEEL +   SW2
7 FREEWHEEL −

(TB2)
OUT 1   1 — M
OUT 2   2

(TB3)
1 HOT — AC INPUT 85–132VAC
2 NEUTRAL
3 EGND

Torque Curves

BDS-36-50-12-5150, MBDC050-012031-120V, 120 VAC

RPM axis: 0, 465, 930, 1395, 1860, 2325, 2790, 3255, 3720, 4185, 4650
Current (Amp) axis: 0, 0.05, 0.1, 0.15, 0.2, 0.25, 0.3, 0.35, 0.4, 0.45, 0.5
Torque (oz-in) axis: 0, 0.4, 0.8, 1.2, 1.6, 2, 2.4, 2.8, 3.2, 3.6, 4

— Torque-Speed
- - - Torque-Current

BDPG-36-40-12V-4000-R51, MBDC050-012031-120V, 120VAC

RPM axis: 0, 9, 18, 27, 36, 45, 54, 63, 72, 81, 90
Current (Amp) axis: 0, 0.013, 0.026, 0.039, 0.052, 0.065, 0.078, 0.091, 0.104, 0.117, 0.13
Torque (oz-in) axis: 0, 4.6, 9.2, 13.8, 18.4, 23, 27.6, 32.2, 36.8, 41.4, 46

— Torque-Speed
- - - Torque-Current

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TECHNICAL SUPPORT

If you should require technical support or if you have problems using any of the equipment covered by this manual, please read the manual completely to see if it will answer the questions you have. If you need assistance beyond what this manual can provide, contact your Local Distributor where you purchased the unit, or contact the factory direct.

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